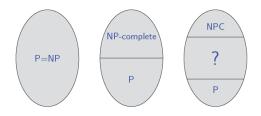
Decision vs. Search Problems

(N	Τl	U.	E.	Đ

NP-Intermediate Problem

• For $P \stackrel{?}{=} NP$ question, which of the following three is most likely?



Theorem 1 (Ladner 1975)

If $P \neq NP$ *then there is a language in* NP *that is neither in* P *not* NP-complete.

- Ladner's theorem gives an "artificial" problem between *P* and *NP*.
- Possible candidates include Graph Isomorphism, Total search problems (Factoring, Nash equilibrium computation, and others)

- For NP-complete problem SAT, suppose we want to compute a satisfying assignment, not just test for satisfiability
- Given a *SAT*-oracle, do the following.
 For φ over variables x₁, ..., x_n, check if φ is satisfiable, if so, try φ with x₁ assigned to 0; otherwise, assign 1 to x₁, then proceed to x₂ etc.
- In a sense, computing a satisfying assignment (a search problem) is no harder than checking SAT (a decision problem).
- Subsequently, we shall see Complexity class *FNP*: functions checkable in poly-time.
 - ► FSAT is FNP-complete
 - HOw about function versions of other NP-complete problems?

Polynomial-time Checkable Relations

- **FNP**: *NP* search problem (a.k.a. function computation problem) is a binary relation *R*(., .) such that
 - R(x, y) is checkable in time polynomial in |x| and |y|
 - ▶ given input *x*, the goal is to find *y* with *R*(*x*, *y*) (*y* is regarded as a certificate)
- **TFNP**: *Total search problem:* Search problem defined for all inputs, i.e.,

$$\forall x \exists y (|y| = poly(|x|), R(x, y))$$

Examples include

- Local-max-cut:
- ► Factoring: input a number *N*, output the prime factorization of *N*.
- Nash: the problem of computing a Nash equilibrium of a game
- ► ...
- **FP**: there exists a det. Ptime algorithm solving it. So given input *x*, it returns a solution *y* so that *R*(*x*, *y*) or it states such an *y* does not exist.

(NTU EE)

Reducibility for Search Problems

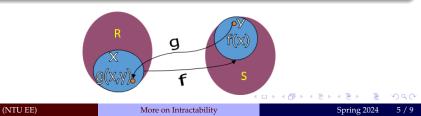
Definition 2

Let *R* and *S* be search problems in FNP. We say that *R* is many-one reducible to *S*, if there exist polynomial-time computable functions f, g such that

$$(f(x), y) \in S \Rightarrow (x, g(x, y)) \in R$$

Theorem 3

FSAT (the problem of finding a satisfying assignment of a boolean formula) is *FNP-complete*.



- If *S* is polynomial-time solvable, then so is *R*.
- Two problems *R* and *S* are (polynomial-time) equivalent, if *R* reduces to *S* and *S* reduces to *R*.
- SAT: *x* is boolean formula, *y* is satisfying assignment. Decision version of SAT is polynomial-time equivalent to search for *y*.

Theorem 4

There is an FNP-complete problem in TFNP if and only if NP = co - NP.

- Factoring (for example) cannot be *NP*-hard unless *NP* = *co NP*. Unlikely! So Factoring is in strong sense "NP-intermediate".
- Other such problems include: Local-Max-Cut, NASH, ...

Polynomial Local Search (PLS)

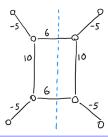
- **Max-Cut**: Find a cut in a weighted graph *G* of maximum size. Decision version is a known NP-complete problem
- Note that **Min-Cut** is solvable in polynomial time.

Algorithm

 $[A, B] \leftarrow$ an arbitrary partition of *V*

While placing some node v to the other side increases the cut weight, move v to the other side

return [A, B]



Generic Local Search Algorithm

• Move step by step from current solution to a "nearby" one

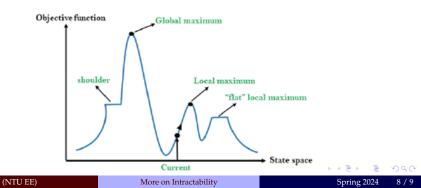
Algorithm

 $s \leftarrow$ some initial solution

While a solution s' in the neighborhood of s is better than s: do

 $s \leftarrow s'$

return s



Key Characteristics of Local Search Algorithm

- Unlike greedy algorithms, we do not require maintaining a feasible solution all the time
 - Greedy algorithm typically build the solution bottom-up
- We need to have a solution so we can compute its value in order to determine whether or not to make a move to a neighboring solution
- Easy to design an algorithm
- Generally, No provable guarantees on the quality of the solution
- Can get a local optimum instead of a global optimum
- The larger the neighborhood, the better the resulting solution and the higher the running time

Theorem 5

 $FP \subseteq PLS \subseteq TFNP \subseteq FNP$.

• Other Local Search Algorithm: Gradient Descent, Simulated Annealing, ...

(NTU EE)