

# Turing Machines

## Recursive/Recursively Enumerable Languages

# Schematic of Turing Machines

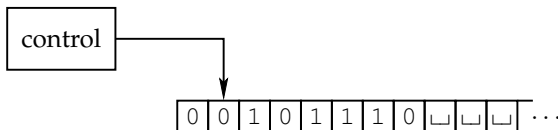


Figure: Schematic of Turing Machines

- A Turing machine has a finite set of control states.
- A Turing machine reads and writes symbols on an infinite tape.
- A Turing machine starts with an input on the left end of the tape.
- A Turing machine moves its read-write head in both directions.
- A Turing machine outputs accept or reject by entering its accepting or rejecting states respectively.
  - ▶ A Turing machine need not read all input symbols.
  - ▶ A Turing machine may not accept nor reject an input.

# Turing Machines

- Consider  $B = \{w\#w : w \in \{0, 1\}^*\}$ .
- $M_1 =$  “On input string  $w$ :
  - 1 Record the first uncrossed symbol from the left and cross it. If the first uncrossed symbol is  $\#$ , go to step 6.
  - 2 Move the read-write head to the symbol  $\#$ . If there is no such symbol, reject.
  - 3 Move to the first uncrossed symbol to the right.
  - 4 Compare with the symbol recorded at step 1. If they are not equal, reject.
  - 5 Cross the current symbol and go to step 1.
  - 6 Check if all symbols to the right of  $\#$  are crossed. If so, accept; otherwise, reject.”

# Turing Machines – Formal Definition

## Definition 1

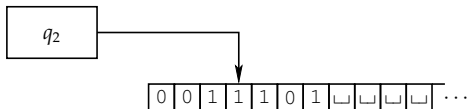
A Turing machine is a 7-tuple  $(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$  where

- $Q$  is the finite set of states;
- $\Sigma$  is the finite input alphabet not containing the blank symbol  $\sqcup$ ;
- $\Gamma$  is the finite tape alphabet with  $\sqcup \in \Gamma$  and  $\Sigma \subseteq \Gamma$ ;
- $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$  is the transition function;
- $q_0 \in Q$  is the start state;
- $q_{\text{accept}} \in Q$  is the accept state; and
- $q_{\text{reject}} \in Q$  is the reject state with  $q_{\text{reject}} \neq q_{\text{accept}}$ .

- We only consider deterministic Turing machines.
- Initially, a Turing machine receives its input  $w = w_1w_2 \cdots w_n \in \Sigma^*$  on the leftmost  $n$  cells of the tape.
- Other cells on the tape contain the blank symbol  $\sqcup$ .

# Computation of Turing Machines

- A configuration of a Turing machine contains its current states, current tape contents, and current head location.
- Let  $q \in Q$  and  $u, v \in \Gamma$ . We write  $uqv$  to denote the configuration where the current state is  $q$ , the current tape contents is  $uv$ , and the current head location is the first symbol of  $v$ .
  - ▶ When we say “the current tape contents is  $uv$ ,” we mean an infinite tape contains  $uv\sqcup\sqcup\cdots\sqcup\cdots$ .
- Consider the configuration  $001q_21101$ . The Turing machine
  - ▶ is at the state  $q_2$ ;
  - ▶ has the tape contents  $0011101$ ; and
  - ▶ has its head location at the second 1 from the left.



# Computation of Turing Machines

- Let  $C_1$  and  $C_2$  be configurations. We say  $C_1$  yields  $C_2$  if the Turing machine can go from  $C_1$  to  $C_2$  in one step.
- Formally, let  $a, b, c \in \Gamma$ ,  $u, v \in \Gamma^*$ , and  $q_i, q_j \in Q$ .

$$\begin{array}{ll} uaq_i bv \text{ yields } uq_j acv & \text{if } \gamma(q_i, b) = (q_j, c, L) \\ q_i bv \text{ yields } q_j cv & \text{if } \gamma(q_i, b) = (q_j, c, L) \\ uaq_i bv \text{ yields } uacq_j v & \text{if } \gamma(q_i, b) = (q_j, c, R) \end{array}$$

- Note the special case when the current head location is the leftmost cell of the tape.
  - ▶ A Turing machine updates the leftmost cell without moving its head.
- Recall that  $uaq_i$  is in fact  $uaq_i \sqcup$ .

# Accept, Reject, and Halting

- The start configuration of  $M$  on input  $w$  is  $q_0w$ .
- An accepting configuration of  $M$  is a configuration whose state is  $q_{\text{accept}}$ .
- A rejecting configuration of  $M$  is a configuration whose state is  $q_{\text{reject}}$ .
- Accepting and rejecting configurations are halting configurations and do not yield further configurations.
  - ▶ That is, a Turing machine accepts or rejects as soon as it reaches an accepting or rejecting configuration.

# Recognizable Languages

- A Turing machine  $M$  accepts an input  $w$  if there is a sequence of configurations  $C_1, C_2, \dots, C_k$  such that
  - ▶  $C_1$  is the start configuration of  $M$  on input  $w$ ;
  - ▶ each  $C_i$  yields  $C_{i+1}$ ; and
  - ▶  $C_k$  is an accepting configuration.
- The language of  $M$  or the language recognized by  $M$  (written  $L(M)$ ) is thus

$$L(M) = \{w : M \text{ accepts } w\}.$$

## Definition 2

A language is Turing-recognizable or recursively enumerable if some Turing machine recognizes it.



# Decidable Languages

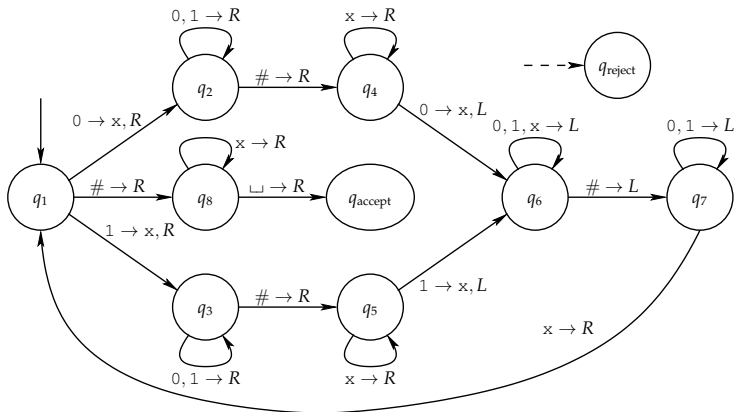
- When a Turing machine is processing an input, there are three outcomes: accept, reject, or loop.
  - ▶ “Loop” means it never enters a halting configuration.
- A deterministic finite automaton or deterministic pushdown automaton have only two outcomes: accept or reject.
- For a nondeterministic finite automaton or nondeterministic pushdown automaton, it can also loop.
  - ▶ “Loop” means it does not finish reading the input ( $\epsilon$ -transitions).
- A Turing machine that halts on all inputs is called a decider.
- When a decider recognizes a language, we say it decides the language.

## Definition 3

A language is Turing-decidable (decidable, or recursive) if some Turing machine decides it.

# Turing Machines – Example

- We now formally define  $M_1 = (Q, \Sigma, \Gamma, \delta, q_1, q_{\text{accept}}, q_{\text{reject}})$  which decides  $B = \{w\#w : w \in \{0, 1\}^*\}$ .
- $Q = \{q_1, \dots, q_{14}, q_{\text{accept}}, q_{\text{reject}}\}$ ;
- $\Sigma = \{0, 1, \#\}$  and  $\Gamma = \{0, 1, \#, x, \sqcup\}$ .



# Turing Machines whose Heads can Stay

- Recall that the transition function of a Turing machine indicate whether its read-write head moves left or right.
- Consider a new Turing machine whose head can stay.
- Hence we have  $\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$ .
- Is the new Turing machine more powerful?
- Of course not, we can always simulate  $S$  by an  $R$  and then an  $L$ .

# Multitape Turing Machines

- A multitape Turing machine has several tapes.
- Initially, the input appears on the tape 1.
- If a multitape Turing machine has  $k$  tapes, its transition function now becomes

$$\delta : Q \times \Gamma^k \rightarrow Q \times \Gamma^k \times \{L, R\}^k$$

- $\delta(q_i, a_1, \dots, a_k) = (q_j, b_1, \dots, b_k, d_1, \dots, d_k)$  means that if the machine is in state  $q_i$  and reads  $a_i$  from tape  $i$  for  $1 \leq i \leq k$ , it goes to state  $q_j$ , writes  $b_i$  to tape  $i$  for  $1 \leq i \leq k$ , and moves the tape head  $i$  towards the direction  $d_i$  for  $1 \leq i \leq k$ .
- Are multitape Turing machines more powerful than single-tape Turing machines?

# Multitape Turing Machines

## Theorem 4

*Every multitape Turing machine has an equivalent single-tape Turing machine.*

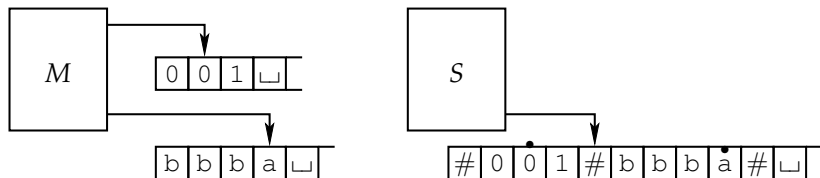
## Proof.

We use a special new symbol  $\#$  to separate contents of  $k$  tapes. Moreover,  $k$  marks are used to record locations of the  $k$  virtual heads.

$S =$  “On input  $w = w_1w_2 \cdots w_n$  :

- 1 Write  $w$  in the correct format:  $\# \overset{\bullet}{w}_1 \overset{\bullet}{w}_2 \cdots \overset{\bullet}{w}_n \# \sqcup \# \sqcup \# \cdots \#$ .
- 2 Scan the tape and record all symbols under virtual heads. Then update the symbols and virtual heads by the transition function of the  $k$ -tape Turing machine.
- 3 If  $S$  moves a virtual head to the right onto a  $\#$ ,  $S$  writes a blank symbol and shifts the tape contents from this cell to the rightmost  $\#$  one cell to the right. Then  $S$  resumes simulation. □

# Multitape Turing Machines



- A “mark” is in fact a different tape symbol.
  - ▶ Say the tape alphabet of the multitape TM  $M$  is  $\{0, 1, a, b, \sqcup\}$ .
  - ▶ Then  $S$  has the tape alphabet  $\{\#, 0, 1, a, b, \sqcup, \overset{\cdot}{0}, \overset{\cdot}{1}, \overset{\cdot}{a}, \overset{\cdot}{b}, \overset{\cdot}{\sqcup}\}$ .

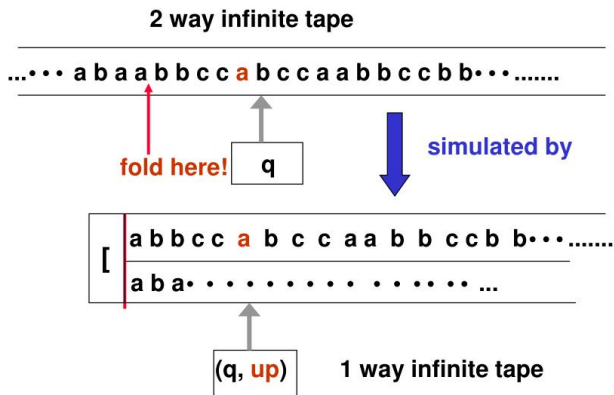
## Corollary 5

*A language is Turing-Recognizable if and only if some multitape Turing machine recognizes it.*

# Turing Machines with 2-way Infinite Tape

## Theorem 6

*A TM with a 2-way infinite tape can be simulated by one with a 1-way infinite tape.*



# Nondeterministic Turing Machines

- A nondeterministic Turing machine has its transition function of type  $\delta : Q \times \Gamma \rightarrow \mathcal{P}(Q \times \Gamma \times \{L, R\})$ .
- Are nondeterministic Turing machines more powerful than deterministic Turing machines?
  - ▶ Recall that nondeterminism does not increase the expressive power in finite automata.
  - ▶ Yet nondeterminism does increase the expressive power in pushdown automata.



# Nondeterministic Turing Machines

## Theorem 7

*Every nondeterministic Turing machine has an equivalent deterministic Turing machine.*

## Proof.

Nondeterministic computation can be seen as a tree. The root is the start configuration. The children of a tree node are all possible configurations yielded by the node. By ordering children of a node, we associate an address with each node. For instance,  $\epsilon$  is the root; 1 is the first child of the root; 21 is the first child of the second child of the root. We simulate an NTM  $N$  with a 3-tape DTM  $D$ . Tape 1 contains the input; tape 2 is the working space; and tape 3 records the address of the current configuration.

Let  $b$  be the maximal number of choices allowed in  $N$ . Define  $\Sigma_b = \{1, 2, \dots, b\}$ . We now describe the Turing machine  $D$ .

# Nondeterministic Turing Machines

## Proof.

- ① Initially, tape 1 contains the input  $w$ ; tape 2 and 3 are empty.
  - ② Copy tape 1 to tape 2.
  - ③ Simulate  $N$  from the start state on tape 2 according to the address on tape 3.
    - ▶ When compute the next configuration, choose the transition by the next symbol on tape 3.
    - ▶ If no more symbol is on tape 3, the choice is invalid, or a rejecting configuration is yielded, go to step 4.
    - ▶ If an accepting configuration is yielded, accept the input.
  - ④ Replace the string on tape 3 with the next string lexicographically and go to step 2. □
- 
- Observe the  $D$  simulates  $N$  by breadth.
    - ▶ Can we simulate by depth?

# Nondeterministic Turing Machines

## Corollary 8

*A language is Turing-recognizable if and only if some nondeterministic Turing machine recognizes it.*

- A nondeterministic Turing machine is a decider if all branches halt on all inputs.
- If the NTM  $N$  is a decider, a slight modification of the proof makes  $D$  always halt. (How?)

## Corollary 9

*A language is decidable if and only if some nondeterministic Turing machine decides it.*

# Schematic of Enumerators

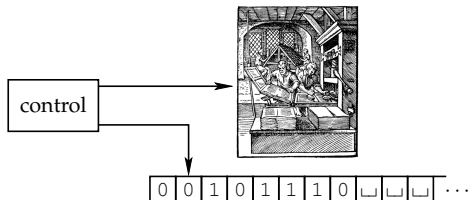


Figure: Schematic of Enumerators

- An enumerator is a Turing machine with a printer.
- An enumerator starts with a blank input tape.
- An enumerator outputs a string by sending it to the printer.
- The language enumerated by an enumerator is the set of strings printed by the enumerator.
  - ▶ Since an enumerator may not halt, it may output an infinite number of strings.
  - ▶ An enumerator may output the same string several times.

# Enumerators

## Theorem 10

*A language is Turing-recognizable if and only if some enumerator enumerates it.*

## Proof.

Let  $E$  be an enumerator. Consider the following TM  $M$ :

$M =$  “On input  $w$  :

- 1 Run  $E$  and compare any output string with  $w$ .
- 2 Accept if  $E$  ever outputs  $w$ .”

Conversely, let  $M$  be a TM recognizing  $A$ . Consider

$E =$  “Ignore the input.

- 1 Repeat for  $i = 1, 2, \dots$ 
  - 1 Let  $s_1, s_2, \dots, s_i$  be the first  $i$  strings in  $\Sigma^*$  (say, lexicographically).
  - 2 Run  $M$  for  $i$  steps on each of  $s_1, s_2, \dots, s_i$ .
  - 3 If  $M$  accepts  $s_j$  for  $1 \leq j \leq i$ , output  $s_j$ .

□

# Enumerators

## Theorem 11

*A language is Turing-decidable if and only if some enumerator enumerates it in lexicographical order.*

## Proof.

Let  $E$  be an enumerator. Consider the following TM  $M$ :

$M =$  "On input  $w$  :

- 1 Run  $E$  and compare each generated output string with  $w$ .
- 2 Accept if  $E$  ever outputs  $w$ ; reject if  $E$  outputs a  $w'$  with  $w < w'$ "

Conversely, let  $M$  be a TM deciding  $A$ , and assume that  $\Sigma = \{0, 1\}$ .

$E =$  "Ignore the input.

- 1 Repeat for  $w = \epsilon, 0, 1, 00, 01, 10, 11, 000, \dots$ 
  - 1 Run  $M$  on  $w$ ;
  - 2 If  $M$  accepts  $w$ , output  $s_j$ ;
  - 3 If  $M$  rejects  $w$ , exit



# Algorithms

- Let us suppose we lived before the invention of computers.
  - ▶ say, circa 300 BC, around the time of Euclid.
- Consider the following problem:  
Given two positive integers  $a$  and  $b$ , find the largest integer  $r$  such that  $r$  divides  $a$  and  $r$  divides  $b$ .
- How do we “find” such an integer?
- Euclid’s method is in fact an algorithm.
- Keep in mind that the concept of algorithms has been in mathematics long before the advent of computer science.

# Hilbert's Problems



- Mathematician David Hilbert listed 23 problems in 1900.
  - ▶ These problems are challenges for mathematicians in 20th century.
- His 10th problem is to devise “a process according to which it can be determined by a finite number of operations,” that tests whether a polynomial has an integral root.
  - ▶ In other words, Hilbert wants to find an algorithm to test whether a polynomial has an integral root.
- If such an algorithm exists, we just need to invent it.
- What if there is no such algorithm?
  - ▶ How can we argue Hilbert's 10th problem has no solution?
- We need a precise definition of algorithms!



# Church-Turing Thesis



- In 1936, two papers came up with definitions of algorithms.
- Alonzo Church used  $\lambda$ -calculus to define algorithms.
  - ▶ If you don't know  $\lambda$ -calculus, take Programming Languages.
- Alan Turing used Turing machines to define algorithms.
  - ▶ If you don't know TM now, please consider dropping this course.
- It turns out that both definitions are equivalent!
- The connection between the informal concept of algorithms and the formal definitions is called the Church-Turing thesis.

# Hilbert's 10th Problem

- In 1970, Yuri Matijasevič showed that Hilbert's 10th problem is not solvable.
  - ▶ That is, there is no algorithm for testing whether a polynomial has an integral root.
- Define  $D = \{p : p \text{ is a polynomial with an integral root}\}$ .
- Consider the following TM:  
 $M = \text{"The input is a polynomial } p \text{ over variables } x_1, x_2, \dots, x_k$ 
  - 1 Evaluate  $p$  on an enumeration of  $k$ -tuple of integers.
  - 2 If  $p$  ever evaluates to 0, accept."
- $M$  recognizes  $D$  but does not decide  $D$ .

# Encodings of Turing Machines

To represent a Turing machine

$$M = (Q, \{0, 1\}, \Gamma, \delta, q_1, B, F)$$

as a binary string, we must first assign integers to the states, tape symbols, and directions  $L$  and  $R$ :

- Assume the states are  $q_1, q_2, \dots, q_r$  for some  $r$ . The start state is  $q_1$ , and the only accepting state is  $q_2$ .
- Assume the tape symbols are  $X_1, X_2, \dots, X_s$  for some  $s$ . Then:  $0 = X_1, 1 = X_2$ , and  $B = X_3$ .
- $L = D_1$  and  $R = D_2$ .
- Encode the transition rule  $\delta(q_i, X_j) = (q_k, X_l, D_m)$  by  $0^i 10^j 10^k 10^l 10^m$ . Note that there are no two consecutive 1s.
- Encode an entire Turing machine by concatenating, in any order, the codes  $C_i$  of its transition rules, separated by 11 :  $C_1 11 C_2 11 \dots C_{n-1} 11 C_n$ .

# Example

$M = (\{q_1, q_2, q_3\}, \{0, 1\}, \{0, 1, B\}, \delta, q_1, B, \{q_2\})$  where  $\delta$  is defined by:  
 $\delta(q_1, 1) = (q_3, 0, R)$ ,  $\delta(q_3, 0) = (q_1, 1, R)$ ,  $\delta(q_3, 1) = (q_2, 0, R)$ , and  
 $\delta(q_3, B) = (q_3, 1, L)$ .

- Codes for the transition rules:

0100100010100 0001010100100  
00010010010100 0001000100010010

- Code for  $M$ : 01001000101001100010101001001  
00010010010100110001000100010010

Given a Turing machine  $M$  with code  $w_i$ , we can now associate an integer to it:  $M$  is the  $i$ th Turing machine, referred to as  $M_i$ . Many integers do not correspond to any Turing machine at all. Examples: 11001 and 001110.

If  $w_i$  is not a valid TM code, then we shall take  $M_i$  to be the Turing machine (with one state and no transitions) that immediately halts on any input. Hence  $L(M_i) = \emptyset$  if  $w_i$  is not a valid TM code.

# Relationship among Languages

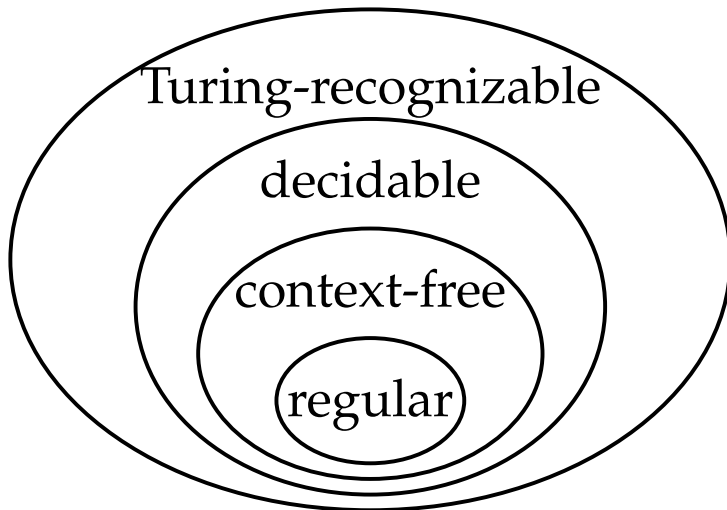


Figure: Relationship among Different Languages

# Acceptance Problem for TM's

- Consider

$$A_{\text{TM}} = \{\langle M, w \rangle : M \text{ is a TM and } M \text{ accepts } w\}$$

- Consider the following TM:  
 $U =$  "On input  $\langle M, w \rangle$  where  $M$  is a TM and  $w$  is a string:
  - 1 Simulate  $M$  on the input  $w$ .
  - 2 If  $M$  enters its accept state, accept; if  $M$  enters its reject state, reject."
- Does  $U$  decide  $A_{\text{TM}}$ ? Why not?
- The TM  $U$  is called the universal Turing machine.

# Counting Arguments

- Recall that  $|\mathbb{N}| = |\mathbb{Z}| = |\Sigma^*| = \aleph_0$  ( $\Sigma$  is finite).
- Also recall that  $|\mathcal{P}(\Sigma^*)| > \aleph_0$ .
  - ▶ Consult your textbook or my notes on discrete mathematics if you are not sure.

## Corollary 12

*Some languages are not Turing-recognizable.*

## Proof.

The set of all Turing machines is countable since each TM  $M$  has an encoding  $\langle M \rangle$  in  $\Sigma^*$ .

The set of all languages over  $\Sigma$  is  $\mathcal{P}(\Sigma^*)$  and hence is uncountable. Hence some languages are not Turing-recognizable. □

- There are in fact uncountably many languages that cannot be recognized by Turing machines.
- Can we find a concrete example?

# Undecidability of the Acceptance Problem for TM's

## Theorem 13

$A_{TM} = \{\langle M, w \rangle : M \text{ is a TM and } M \text{ accepts } w\}$  is not a decidable language.

## Proof.

Suppose there is a TM  $H$  deciding  $A_{TM}$ . That is,

$$H(\langle M, w \rangle) = \begin{cases} \text{accept} & \text{if } M \text{ accepts } w \\ \text{reject} & \text{if } M \text{ does not accept } w \end{cases}$$

Consider the following TM:

$D =$  "On input  $\langle M \rangle$  where  $M$  is a TM:

- 1 Run  $H$  on the input  $\langle M, \langle M \rangle \rangle$ .
- 2 If  $H$  accepts, reject. If  $H$  rejects, accept."

Consider

$$D(\langle D \rangle) = \begin{cases} \text{accept} & \text{if } D \text{ does not accept } \langle D \rangle \\ \text{reject} & \text{if } D \text{ accepts } \langle D \rangle \end{cases}$$

A contradiction. □



# A Turing-unrecognizable Language

- A language is co-Turing-recognizable if it is the complement of a Turing-recognizable language.

## Theorem 14

*A language is decidable if and only if it is Turing-recognizable and co-Turing-recognizable.*

## Proof.

If  $A$  is decidable, then  $A$  and  $\bar{A}$  are both recognizable. Since  $\bar{\bar{A}} = A$ ,  $A$  is Turing-recognizable and co-Turing-recognizable.

Now suppose  $A$  and  $\bar{A}$  are Turing-recognizable by  $M_1$  and  $M_2$  respectively. Consider

$M =$  "On input  $w$ :

- 1 Run both  $M_1$  and  $M_2$  on the input  $w$  **in parallel**.
- 2 If  $M_1$  accepts, accept; if  $M_2$  accepts; reject."

□

# A Turing-unrecognizable Language

## Corollary 15

$\overline{A_{TM}}$  is not Turing-recognizable.

## Proof.

$A_{TM}$  is Turing-recognizable. If  $\overline{A_{TM}}$  is Turing-recognizable,  $A_{TM}$  is both Turing-recognizable and co-Turing-recognizable. By Theorem 14,  $A_{TM}$  is decidable. A contradiction.  $\square$